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# Periodically Correlated Processes

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## Introduction

**DEFINITION 1.1** *The stochastic process  $\{X(t, \omega), t \in I\}$  defined on the probability space  $L_2(\Omega, F, P)$  is called periodically correlated (PC) with period  $T$  if  $T$  is the smallest integer such that:*

$$E\{X(u)\} = m(u) = m(u + T),$$

$$E\{(X(u) - m(u))\overline{(X(v) - m(v))}\} = R(u, v) = R(u + T, v + T),$$

for every  $(u, v) \in I \times I$ .

A stationary sequence is periodically correlated with  $T = 1$ .

## Introduction cont.

- PC processes are a class of processes which are in general nonstationary but exhibit many of the properties of stationary processes
- PC processes have been used as models in meteorology, radio physics and communications engineering
- PC processes have been called periodically nonstationary, cyclostationary, periodically stationary and processes with periodic structure

## Simple models for PC sequences

- If  $X(t) \in L_2(\Omega, F, P)$  is a periodic sequence with period  $T$ , then  $X(t)$  is PC.
- If  $X(t) \in L_2(\Omega, F, P)$  is wide sense stationary with  $E\{X(t)\} = 0$  and  $f(t)$  is a scalar periodic sequence  $f(t) = f(t + T)$ , then

$$Y(t) = f(t) + X(t)$$

is PC with period  $T$ .

## Simple models for PC sequences cont.

- If  $X(t) \in L_2(\Omega, F, P)$  is wide sense stationary with  $E\{X(t)\} = 0$  and  $f(t)$  is a scalar periodic sequence  $f(t) = f(t + T)$ , then

$$Y(t) = f(t)X(t)$$

is PC with period  $T$ .

- If  $X(t) \in L_2(\Omega, F, P)$  is wide sense stationary with  $E\{X(t)\} = 0$  and  $f(t)$  is a scalar periodic sequence  $f(t) = f(t + T)$  taking values in the index set, then

$$Y(t) = X(t + f(t))$$

is PC with period  $T$ .

## Spectral representation of PC processes

Gladyshev (1961) showed that the covariance  $R_X(m, n)$  of PC processes has representation

$$R_X(m, n) = \int_0^{2\pi} \int_0^{2\pi} e^{im\omega_1 - in\omega_2} f_Z(\omega_1, \omega_2) d\omega_1 d\omega_2 \quad (1)$$

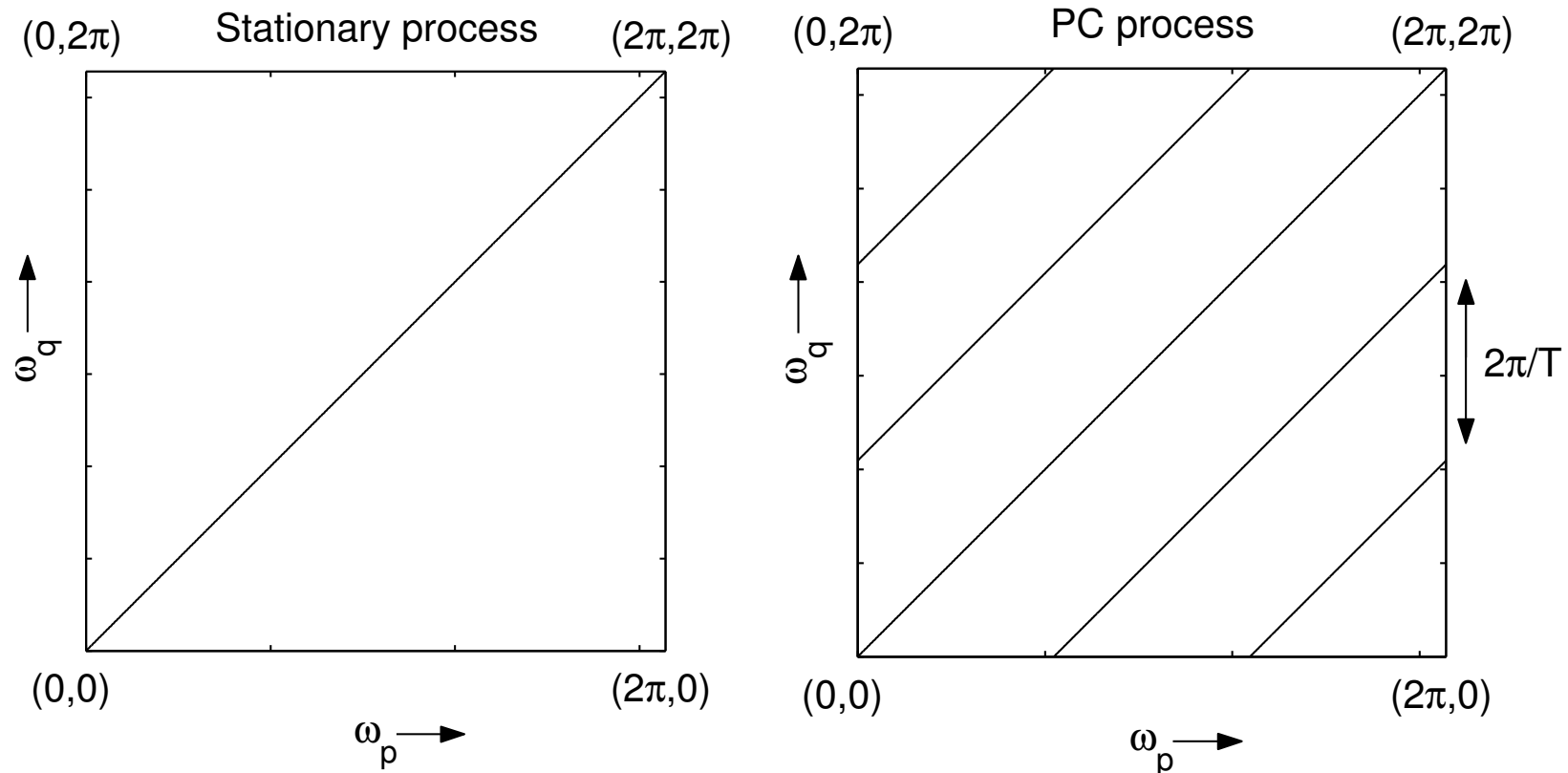
The support of spectral density  $f_Z(\omega_1, \omega_2)$  is then contained in the set of  $2[T] - 1$  diagonal lines

$$S = \bigcup_{k \in \mathbb{Z}} \{[\omega_1, \omega_2] \in [0, 2\pi) \times [0, 2\pi) : \omega_1 = \omega_2 + 2k\pi/T\}$$

where  $T$  is the period of the correlation function. It follows that the spectral density function is given by

$$f_Z(\omega_1, \omega_2) = \begin{cases} f_Z(\omega_1, \omega_2) & [\omega_1, \omega_2] \in S \\ 0 & [\omega_1, \omega_2] \notin S \end{cases}$$

## Spectral representation of PC processes cont.



## Measuring periodic correlation

To investigate the presence of periodic correlation we can use a statistic which is called *sample coherence* and is defined as

$$|\hat{\gamma}(p, q, M)|^2 = \frac{|\sum_{m=0}^{M-1} I_N(\omega_{p+m}) \overline{I_N(\omega_{q+m})}|^2}{\sum_{m=0}^{M-1} |I_N(\omega_{p+m})|^2 \sum_{m=0}^{M-1} |I_N(\omega_{q+m})|^2}, \quad (2)$$

- $0 < p, q \leq N$ ,  $N$  is the sample length
- $M$  is the smoothness coefficient

It takes only real values between 0 and 1. For PC processes the values taken on the support lines are significantly different from those taken for the intermediate frequencies.



## Measuring periodic correlation cont.

There are two standard graphical tools for detecting periodic correlation. Both are based on sample coherence.

- The *coherent statistic* is defined as  $|\hat{\gamma}(0, d, N)|^2$ , where  $d = |q - p|$ .
- The *incoherent statistic* is given by

$$\delta(d, M) = \frac{1}{L + 1} \sum_{p=0}^L |\hat{\gamma}(pM, pM + d, M)|^2 ,$$

where  $L = \left[ \frac{N-1-d}{M} \right]$ .

Peaks in one-dimensional plots of both statistics indicate periods of length  $T = 1/d$ .

## Measuring periodic correlation cont.

We propose the *measure of fitness (MoF)* statistic

$$MoF(d, M) = \frac{1}{N} \sum_{p=1}^N \kappa_{\alpha}(p, p + d, M)$$

where

- $\kappa_{\alpha}(p, q, M) = \begin{cases} 1 & |\hat{\gamma}(p, q, M)|^2 \geq \hat{c}_{\alpha} \\ 0 & |\hat{\gamma}(p, q, M)|^2 < \hat{c}_{\alpha} \end{cases}$
- $\alpha$  is the confidence level
- $\hat{c}_{\alpha}$  is the estimator of the critical value

The estimator  $\hat{c}_{\alpha}$  is computed using the *Moving Blocks Bootstrap (MBB)* procedure

## Measuring periodic correlation cont.

For a sample  $\{X_1, \dots, X_N\}$  the method for computing estimator  $\hat{c}_\alpha$  based on the MBB procedure consists of the following

- denote blocks of length  $b$  as  $B_i = (X_i, \dots, X_{i+b-1})$ ,  
 $i = 1, \dots, N - b + 1$
- draw from the set  $\{B_i : i = 1, \dots, N - b + 1\}$  a number  $k = \lceil N/b \rceil$  of blocks and construct the bootstrap sample  $\{X_1^*, \dots, X_l^*\} = \{B_1^*, \dots, B_k^*\}$  by gluing the blocks together
- compute the coherence statistic  $|\hat{\gamma}_i^*(p, q, M)|^2$  at each point  $(p, q)$ ,  $B$  times for each bootstrap sample
- approximate the critical value  $\hat{c}_\alpha$  as the  $1 - \alpha$  quantile of the bootstrap distribution. It is the  $[\alpha \cdot N]$ -th largest value of the sequence  $\{|\hat{\gamma}_1^*(p, q, M)|^2, \dots, |\hat{\gamma}_B^*(p, q, M)|^2\}$

# Example 1

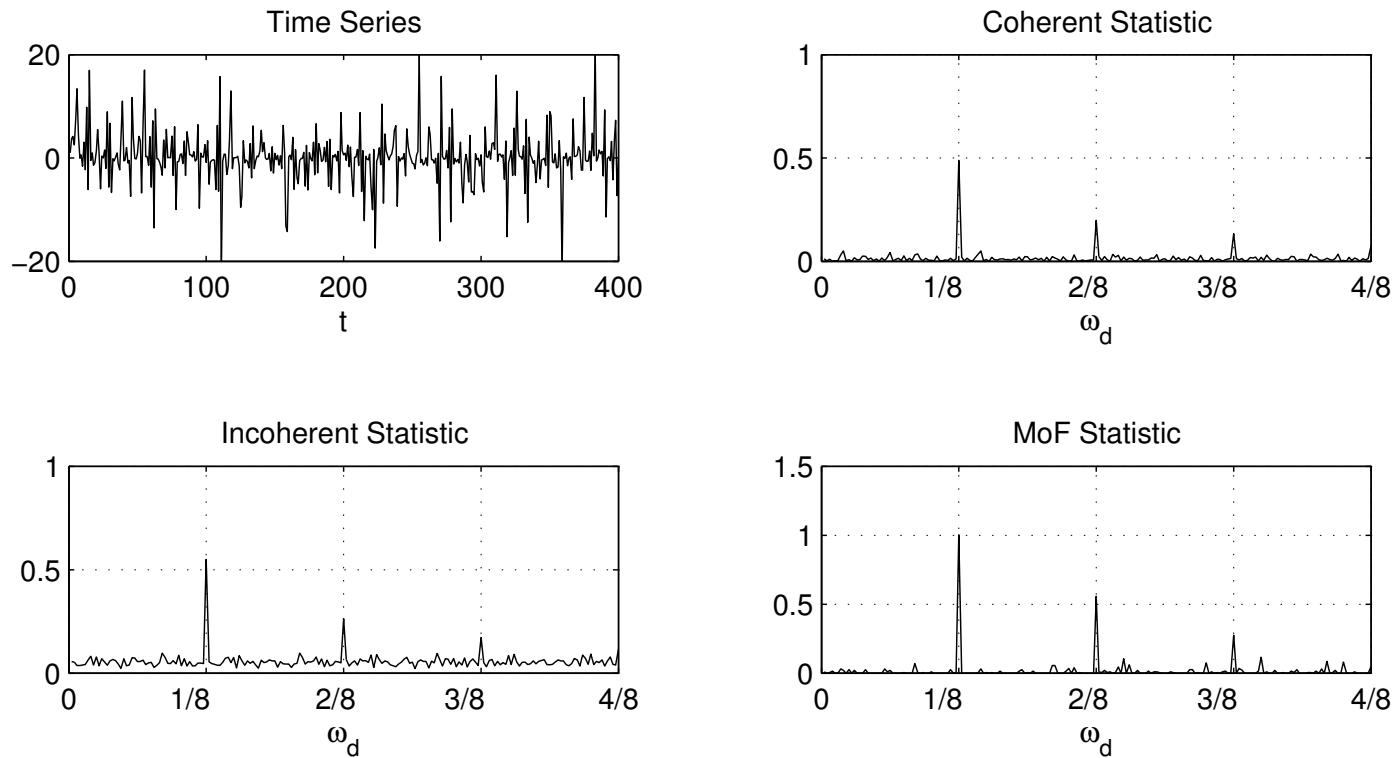


Figure 1: PC process  $X_n = S_n \cdot f^2(n)$ , where  $f(n) = \text{mod}(n, 8)$ . The test parameters:  $M=20$ ,  $B=100$ ,  $\alpha=0.01$ ,  $N=400$ .

## Example 2

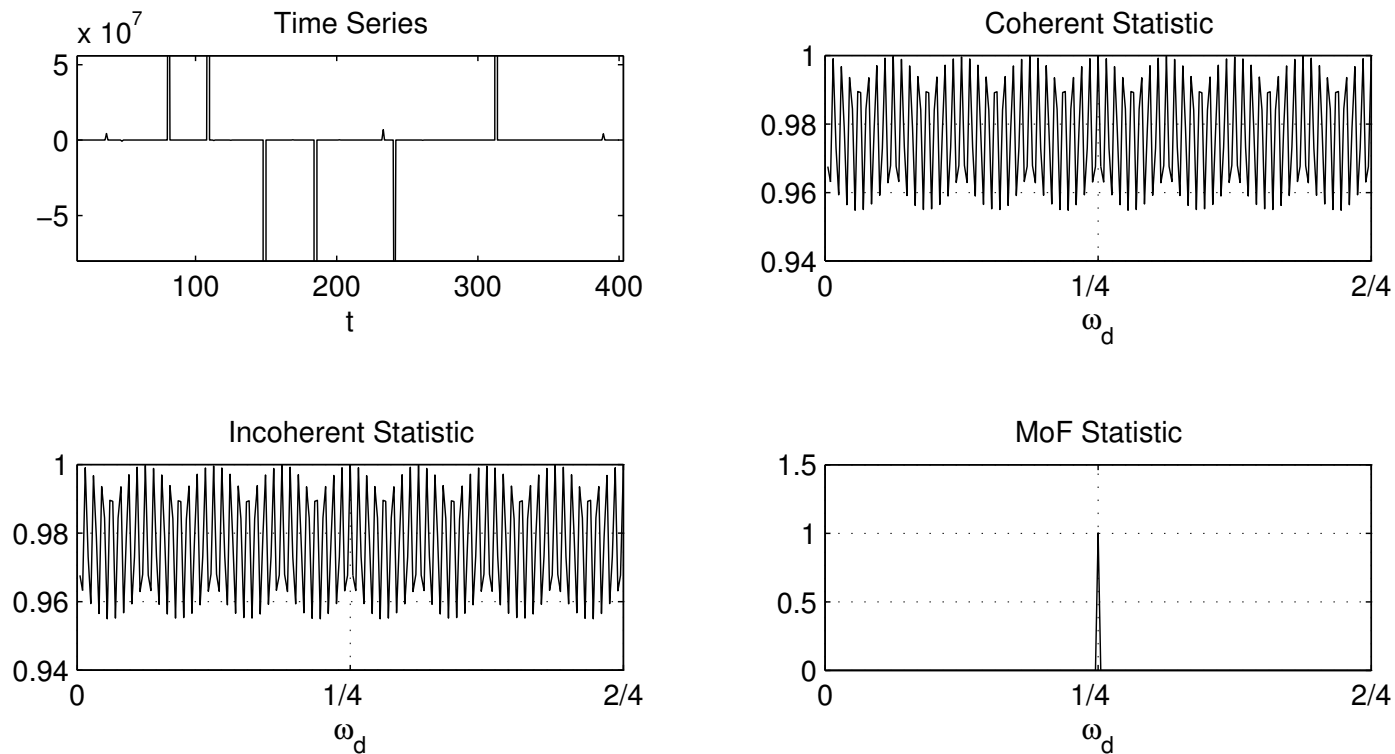


Figure 2: PC process  $X_n = S_n \cdot \exp[8 \cdot \{1 + \sin(\frac{\pi n}{2}) \cdot \frac{4}{5} \xi_n\}]$ . The test parameters:  $M=20$ ,  $B=100$ ,  $\alpha=0.01$ ,  $N=400$ .

## Example 3

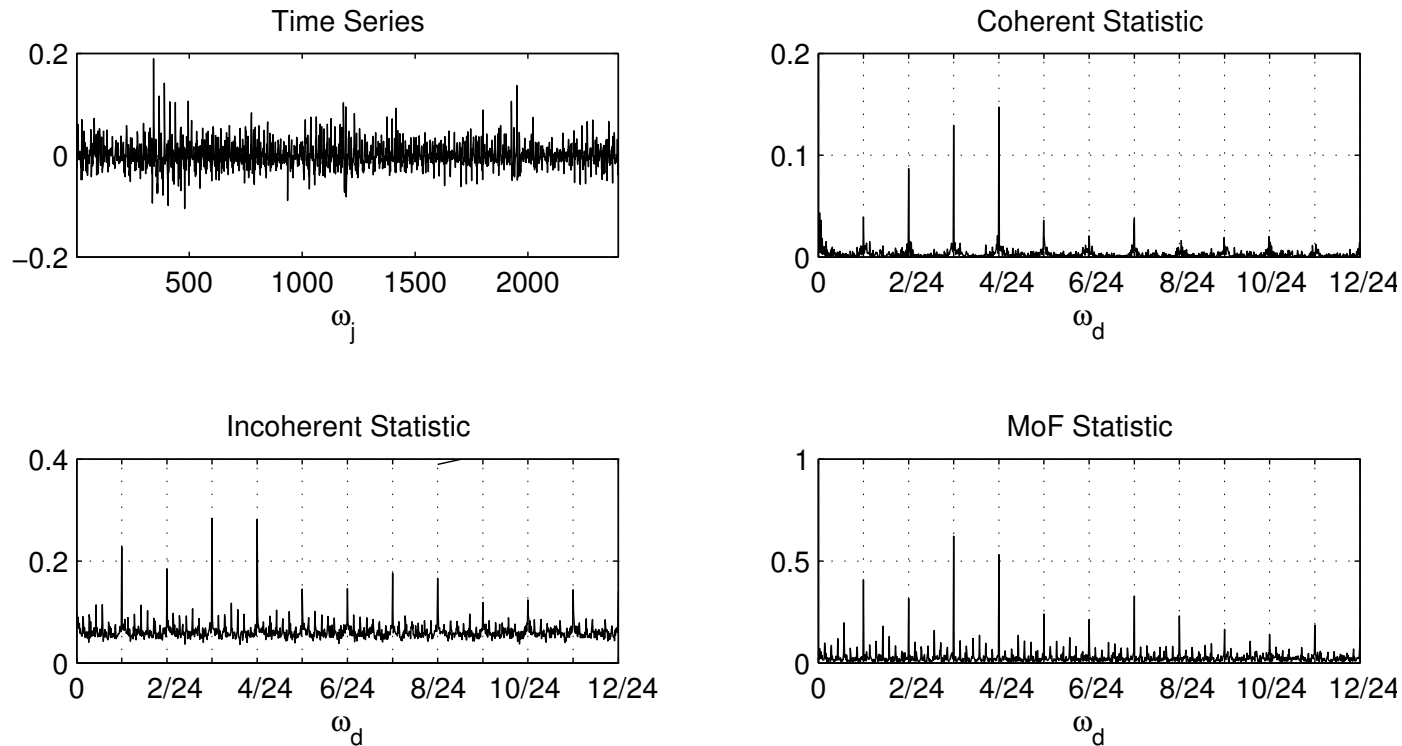


Figure 3: Hourly returns of Nord Pool electricity spot prices during the period January 1st, 1997 – December 25th, 2001(100 days). The test parameters:  $M=20$ ,  $B=100$  and  $\alpha=0.01$ ,  $N=2400$ .

## Example 4

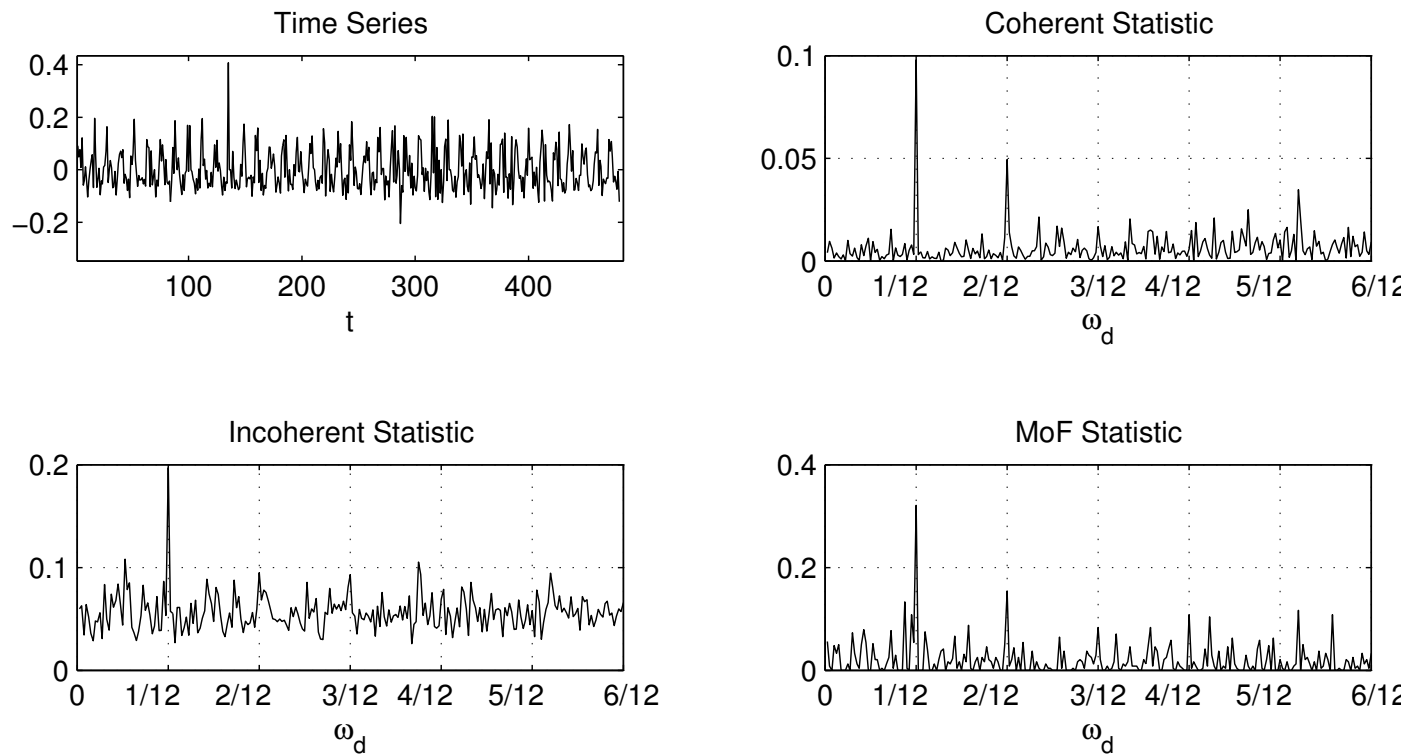


Figure 4: Monthly AROSA Switzerland Ozone levels. The test parameters:  $M=20$ ,  $B=100$  and  $\alpha=0.01$ ,  $N=480$ .

## Example 5

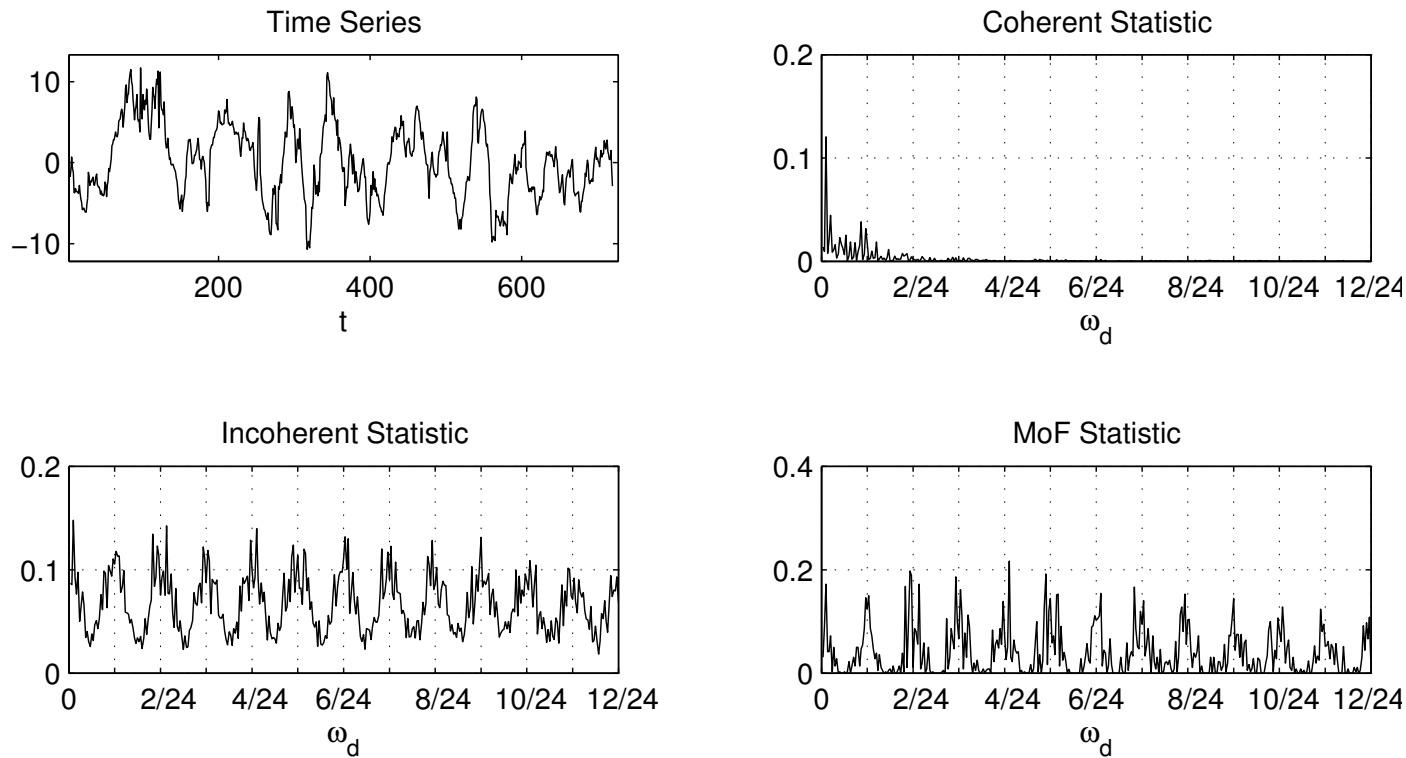


Figure 5: Hourly temperatures in Wrocław from January 1993. The test parameters:  $M=20$ ,  $B=100$  and  $\alpha=0.01$ ,  $N=720$ .



## Example 6

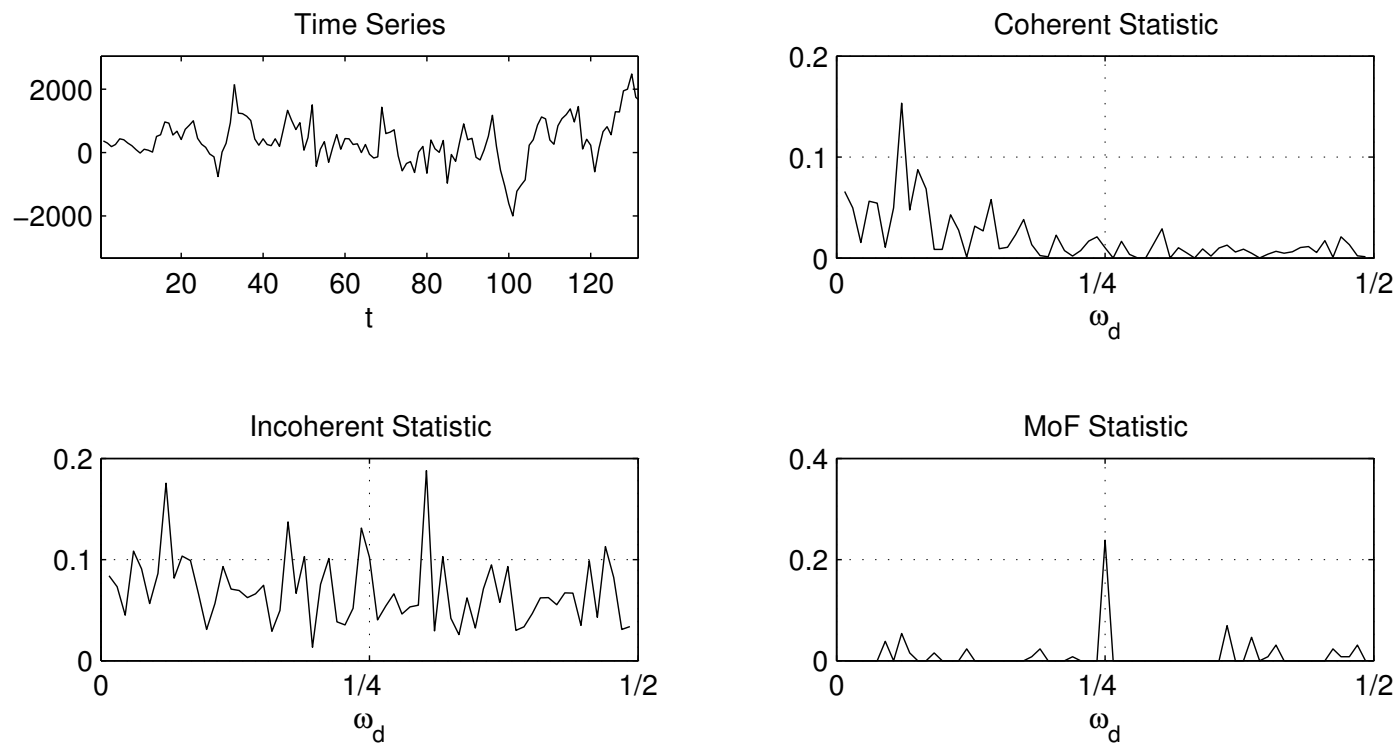


Figure 6: Quarterly real total investment in the United Kingdom 1955-1988. The test parameters:  $M=20$ ,  $B=100$  and  $\alpha=0.01$ ,  $N=138$ .

## PARMA models cont.

**DEFINITION 1.2** *The system PARMA( $p, q$ ) is defined as:*

$$X(n) - \sum_{k=1}^p \phi_k(n) X(n-k) = \sum_{k=0}^{q-1} \theta_k(n) \xi_{n-k}, \quad (3)$$

*where the sequences  $\{\phi_k(n)\}$  and  $\{\theta_k(n)\}$  are periodic in  $n$  with the same period  $T$  and  $\xi_k$  is uncorrelated sequence of random variables with mean 0 and unit variance.*

## PARMA vs. VARMA

We arrange coefficients of the left and right-hand sides of (3) into  $T \times (l + 1)T$  i  $T \times (r + 1)T$  matrices as follows

$$\begin{bmatrix} 1 & -\phi_1(0) & -\phi_2(0) & \dots & -\phi_p(0) & 0 & \dots & 0 \\ 0 & 1 & -\phi_1(1) & \dots & -\phi_{p-1}(1) & -\phi_p(1) & \dots & 0 \\ 0 & 0 & 1 & -\phi_1(2) & \dots & -\phi_{p-2}(2) & \dots & 0 \\ & \vdots & & & \vdots & & & \\ 0 & 0 & \dots & 1 & -\phi_1(T-1) & \dots & -\phi_p(T-1) & \dots \end{bmatrix}$$

## PARMA vs. VARMA cont.

$$\begin{bmatrix} \theta_0(0) & \theta_1(0) & \dots & \theta_q(0) & 0 & 0 & 0 & 0 & \dots & 0 \\ 0 & \theta_0(1) & \theta_1(1) & \dots & \theta_q(1) & 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & \theta_0(2) & \theta_1(2) & \dots & \theta_q(2) & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 0 & \theta_1(T-1) & \dots & \theta_q(T-1) & \dots & 0 \end{bmatrix}.$$

## PARMA vs. VARMA cont.

We denote the consecutive  $T \times T$  blocks of the two matrices by  $\Phi_0, \dots, \Phi_l$  and  $\Theta_0, \dots, \Theta_r$ , respectively, then (3) can be written as the  $T$ -dimensional vector ARMA (VARMA) system

$$\mathbf{X}(n) - \sum_{k=1}^l \Phi_k \mathbf{X}(n-k) = \sum_{k=0}^r \Theta_k \Xi_{n-k} \quad (4)$$

where

$$\mathbf{X}(n) = [x(nT), x(nT-1), \dots, x((n-1)T+1)]^t$$

and

$$\Xi_n = [\xi_{nT}, \xi_{nT-1}, \dots, \xi_{(n-1)T+1}]^t.$$

## Example 7

We consider PARMA(1,1) model with the period  $T = 2$  given by the formula:

$$X(n) - \phi(n)X(n-1) = \theta_0(n)\xi_n + \theta_1(n)\xi_{n-1}.$$

## Example 7 cont.

Then the adequate VARMA model has the following matrices of coefficients:

$$\Phi_1 = \begin{bmatrix} 1 & -\phi(0) \\ 0 & 1 \end{bmatrix}$$

$$\Phi_2 = \begin{bmatrix} 0 & 0 \\ -\phi(1) & 0 \end{bmatrix}$$

$$\Theta_0 = \begin{bmatrix} \theta_0(0) & \theta_1(0) \\ 0 & \theta_0(1) \end{bmatrix}$$

$$\Theta_1 = \begin{bmatrix} 0 & 0 \\ \theta_1(1) & 0 \end{bmatrix}.$$

## ARMA(p,q) models with varying coefficients

**DEFINITION 1.3** *An ARMA(p,q) system with varying coefficients is a system of linear equations*

$$X(n) - \sum_{k=1}^p b_k(n)X(n-k) = \sum_{k=0}^{q-1} a_k(n)\xi_{n-k}, \quad (5)$$

where where  $(b_k(n))$ ,  $k = 1, \dots, p$  and  $(a_k(n))$ ,  $k = 0, \dots, q - 1$ , are sequences of complex numbers, and  $(\xi_n)$  is a sequence of uncorrelated complex random variables with mean zero and unit variances.



## ARMA(p,q) models with varying coefficients cont.

Let

$$B_n = \begin{bmatrix} b_1(n) & b_2(n) & \dots & b_{p-1}(n) & b_p(n) \\ 1 & 0 & \dots & 0 & 0 \\ 0 & 1 & \dots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & 1 & 0 \end{bmatrix}$$

$$\mathbf{B}_k^n = B_n B_{n-1} \dots B_k, \quad n \geq k$$

## ARMA(p,q) models with varying coefficients cont.

$$\mathbf{X}(n) = [X(n), X(n-1), \dots, X(n-p+1)]'$$

$$Y_n = \left[ \sum_{p=0}^{q-1} a_p(n) \xi_{n-p}, 0, \dots, 0 \right]'$$

$$\Xi_n = [\xi_n, 0, \dots, 0]'$$

$$\mathbf{a}_j(n) = \begin{bmatrix} a_j(n) & 0 & \cdots & 0 \\ 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 0 \end{bmatrix}.$$

## ARMA(p,q) models with varying coefficients cont.

Then system (5) has the equivalent form:

$$\mathbf{X}(n) - B_n \mathbf{X}(n-1) = \mathbf{Y}_n. \quad (6)$$

The following theorem gives the sufficient and necessary conditions for existence of a unique bounded solution of equation (6).

## Unique and bounded solutions of ARMA(p,q) models with varying coefficients

**THEOREM 1.1** *System (6) has a unique bounded solution iff:*

- I.** (i)  $\sup_{n \geq 1} \|\mathbf{B}_1^n\| = \infty$  and  
(ii)  $\sup_{n \in \mathbb{Z}} \sum_{s=2-q}^{\infty} \left\| \sum_{j=\max(1,s)}^{q-1+s} (\mathbf{B}_{n+1}^{n+j})^{-1} \mathbf{a}_{j-s}(n+j) \right\|^2 < \infty,$   
or
- II.** (i)  $\sup_{n \leq -1} \|\mathbf{B}_n^0\|^{-1} = \infty$  and  
(ii)  $\sup_{n \in \mathbb{Z}} \sum_{s=0}^{\infty} \left\| \sum_{j=-s}^{\min(0,q-1-s)} \mathbf{B}_{n+j+1}^n \mathbf{a}_{s+j}(n+j) \right\|^2 < \infty.$

## Unique and bounded solutions of ARMA(p,q) models with varying coefficients cont.

**THEOREM 1.2** *If I is satisfied then the solution has the form*

$$\mathbf{X}(n) = - \sum_{s=2-q}^{\infty} \left[ \sum_{j=\max(1,s)}^{q-1+s} (\mathbf{B}_{n+1}^{n+j})^{-1} \mathbf{a}_{j-s}(n+j) \right] \Xi_{n+s}.$$

*If II is satisfied then the solution is given by*

$$\mathbf{X}(n) = \sum_{s=0}^{\infty} \left[ \sum_{j=-s}^{\min(0,q-1-s)} \mathbf{B}_{n+j+1}^n \mathbf{a}_{s+j}(n+j) \right] \Xi_{n-s}.$$

## Unique and bounded solutions of ARMA(p,q) models with varying coefficients cont.

**THEOREM 1.3** *Let  $P = B_1 B_2 \dots B_T$ . System (5) has a bounded solution iff  $\|P\| \neq 1$ . The solution is unique and periodically correlated with period  $T$ .*

## Yule-Walker equation for ARMA(p,q) models

**THEOREM 1.4** (*Yule-Walker equation*)

Let  $\{X(n), n \in \mathbb{Z}\}$  be the solution of system ARMA(p,q) with varying coefficients and  $\|P\| = \|\mathbf{B}_1^T\| < 1$ , then the correlation function satisfies the Yule-Walker equation:

$$R(n, m) - \sum_{j=1}^p b_j(n) R(n - j, m) = \sum_{j=0}^{q-1} a_j(n) U_{m-n+j}(m),$$

where  $U_j(n)$  is the first coefficients of the following vector

$$L_s(n) = \sum_{j=-s}^{\min(0, q-1-s)} \mathbf{B}_{n+j+1}^n \mathbf{a}_{s+j}(n+j) [1 \ 0 \ 0 \ \dots \ 0]'$$

## Example 8

We consider the Nord Pool data of price of energy. We fit the best PAR(p) model

$$X(n) - \sum_{j=1}^p b_j(n) X(n-j) = \xi_n.$$

The best PAR(p) model with respect to Bayesian information criterion is the PAR(5) model. The  $P$  matrix has the following form

$$P = \begin{bmatrix} 3.3689 & -2.5041 & 0.7109 & 0.0821 & -0.0315 \\ 3.3866 & -2.5174 & 0.7147 & 0.0825 & -0.0317 \\ 3.4027 & -2.5271 & 0.7180 & 0.0830 & -0.0318 \\ 3.4109 & -2.5232 & 0.7193 & 0.0835 & -0.0319 \\ 3.4041 & -2.5152 & 0.7177 & 0.0834 & -0.0318 \end{bmatrix}$$



## Example 8 cont.

The norm of  $P$  is less than 1, therefore there is unique bounded solution of the system, moreover the solution is given by the equation

$$\mathbf{X}(n) = \sum_{s=0}^{\infty} \mathbf{B}_{n-s+1}^n \Xi_{n-s}$$

for the fitted parameters  $b_j(n)$ .